

Overland Millimeter-wave Retrievals of Total Column Water Vapor

Alan B Tanner (presenting), Pekka P Kangaslahti, Javier Bosch-Lluis
Jet Propulsion Laboratory, California Institute of Technology

Steven C. Reising
Colorado State University

Overland Total Column Water Vapor Radiometer

Alan Tanner

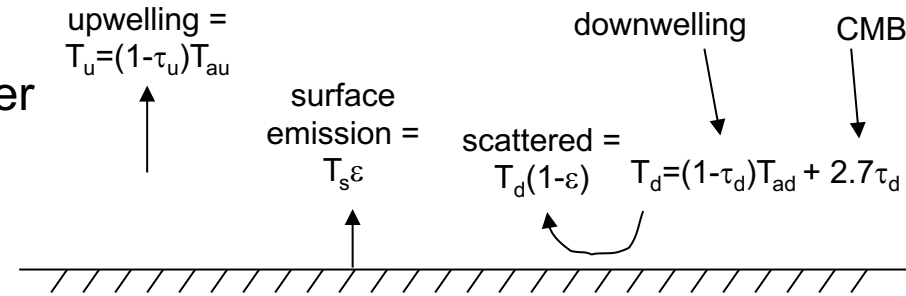
- Problem: Conventional downward viewing mm-wave atmospheric soundings can't measure water in lower troposphere over land (Due to high surface emissivity, insufficient land - air temperature difference, and unknown scattering)
- Solution: New technique measures water relative to oxygen by matching image contrasts among bands between 118 and 183 GHz.
- Tested using data from Colorado State University 'HAMMR' radiometer aboard Twin-Otter aircraft.

Problem:

Microwave Water Vapor Retrievals presently of two kinds:

1) 18, 23, 34 GHz ideal for total vapor over oceans

- Enabled by high ocean surface reflection
- Won't work over land



2) Vertical sounding / profiling near 183 GHz

- High opacity and high temperature lapse rate provide good sounding above lower troposphere
- Lower troposphere obscured over land
- Yet most water is in lower troposphere!

Over land:

Emissivity and surface temperature highly variable

Unknown surface scattering leads to unknown mix of one-way versus two-way path through atmosphere

Proposed solution:

Use known oxygen absorption as a reference to estimate opacity due to water vapor

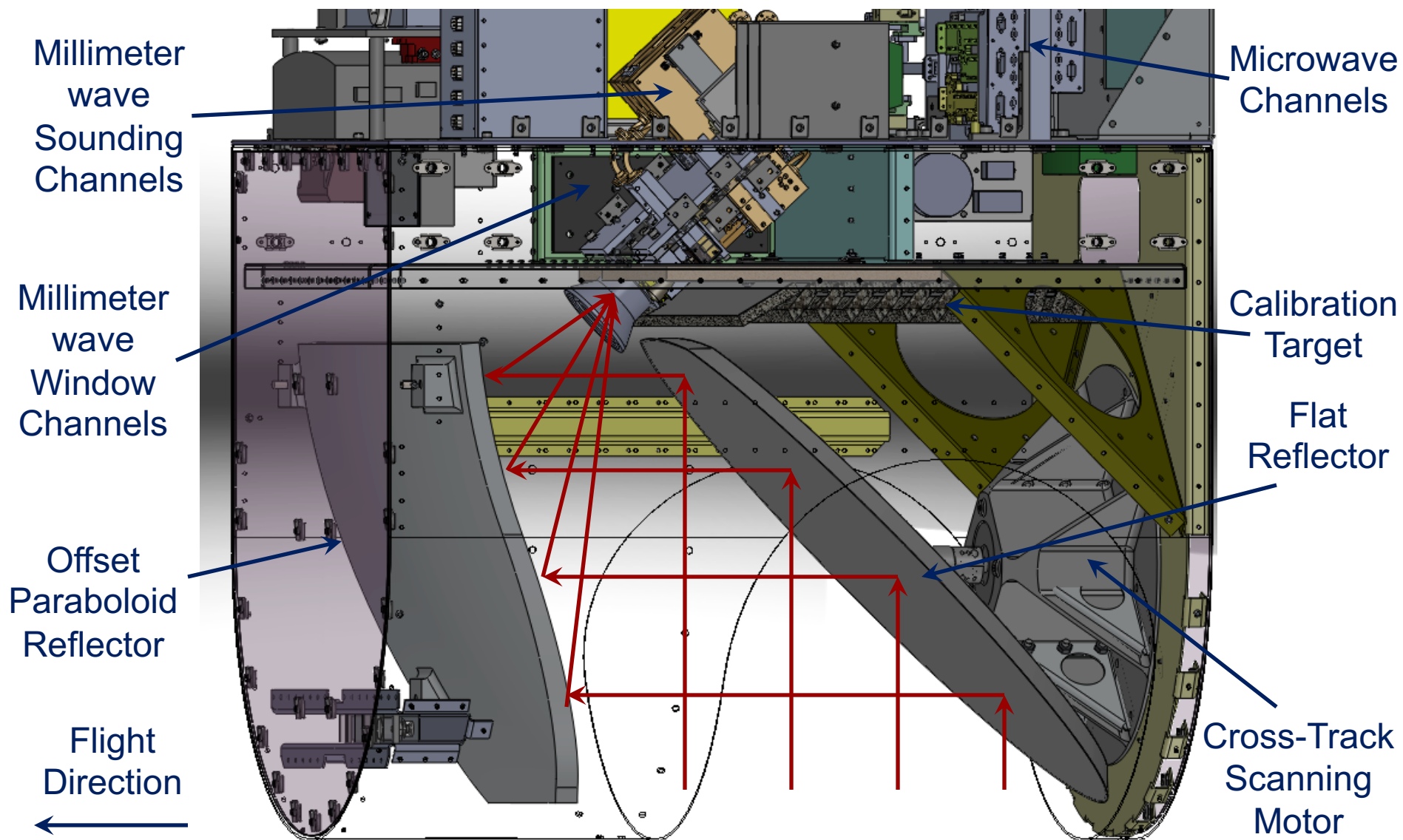
Compare images of the land in bands above 118 GHz with coincident images below 183 GHz

To first order, atmosphere is treated as simple attenuating “slab”

Two “slabs” of equal opacity and temperature will attenuate and emit equally, so land images will also be equal— regardless of surface scattering or emission.

Process is analogous to comparing two pieces of tinted glass: You can judge when two pieces have the same ‘darkness’ or attenuation, even if you don’t have any other objective measure of the scene behind the glass.

Colorado State University HAMMR Instrument

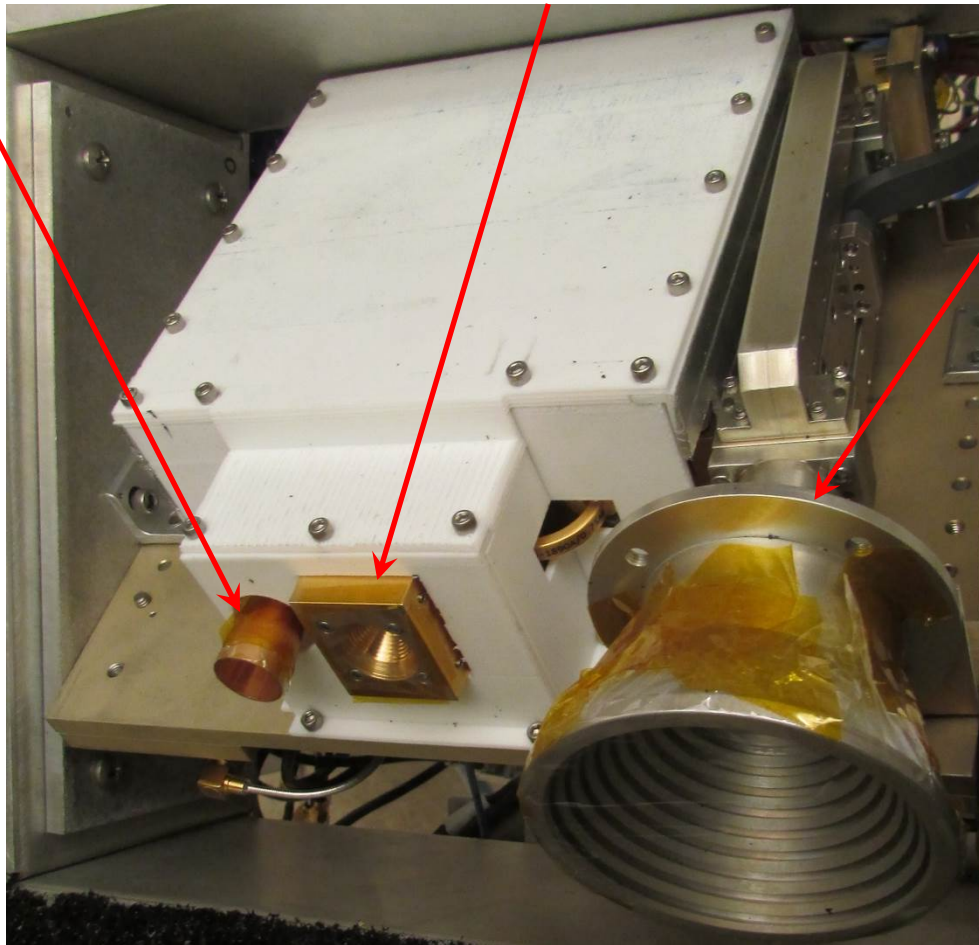


Three Feed Horn Antennas for Three Frequency Channel Sets

High-Frequency Millimeter-wave Sounding Channels
(118 and 183 GHz)

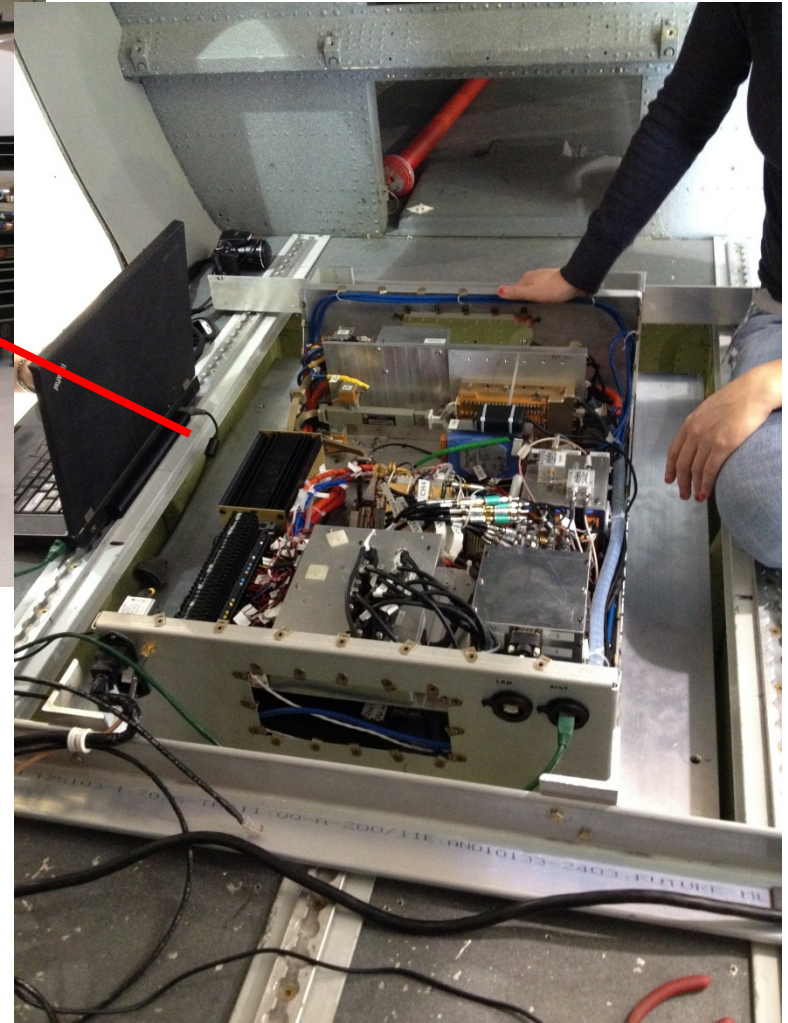
High-Frequency Millimeter-Wave Window Channels
(90, 130 and 168 GHz)

Low-Frequency Microwave channels
(18.7, 23.8 and 34 GHz)





Installation on Twin Otter



Field Campaign



HAMMR installation
at TOI, Grand
Junction, CO
Nov 03, 2014



Salem , OR
Nov 10, 2014



Pre-flight LN2 Calibration Salem , OR
Nov 10, 2014

HAMMR channels

Radiometer	Frequency	Internal Target Standard Deviation	Pyramidal Target Standard Deviation
Microwave QV	18.7 GHz	0.3	0.3
	23.8 GHz	0.2	0.1
	34.0 GHz	0.3	0.4
Microwave QH	18.7 GHz	0.4	0.5
	23.8 GHz	0.3	0.2
	34.0 GHz	0.2	0.1
Millimeter-Wave Window	90 GHz	0.2	0.2
	130 GHz	N/A	N/A
	168 GHz	0.6	1
Millimeter-Wave Sounding 118.75 GHz	0 MHz	N/A	N/A
	250 MHz	0.4	0.6
	500 MHz	0.2	0.5
	+1 GHz	0.2	0.2
	+2 GHz	0.3	0.5
	+3 GHz	0.3	0.5
	+4 GHz	0.3	0.7
	+5 GHz	0.2	0.7
	+6 GHz	N/A	N/A
	+7 GHz	N/A	N/A
	+8 GHz	N/A	N/A
Millimeter-Wave Sounding 183.31 GHz	-1GHz	0.4	0.5
	-2 GHz	0.3	0.4
	-3 GHz	0.4	0.3
	-4 GHz	0.3	0.2
	-5 GHz	0.2	0.4
	-6 GHz	0.3	0.3
	-7 GHz	0.4	0.3
	-8 GHz	0.2	0.4

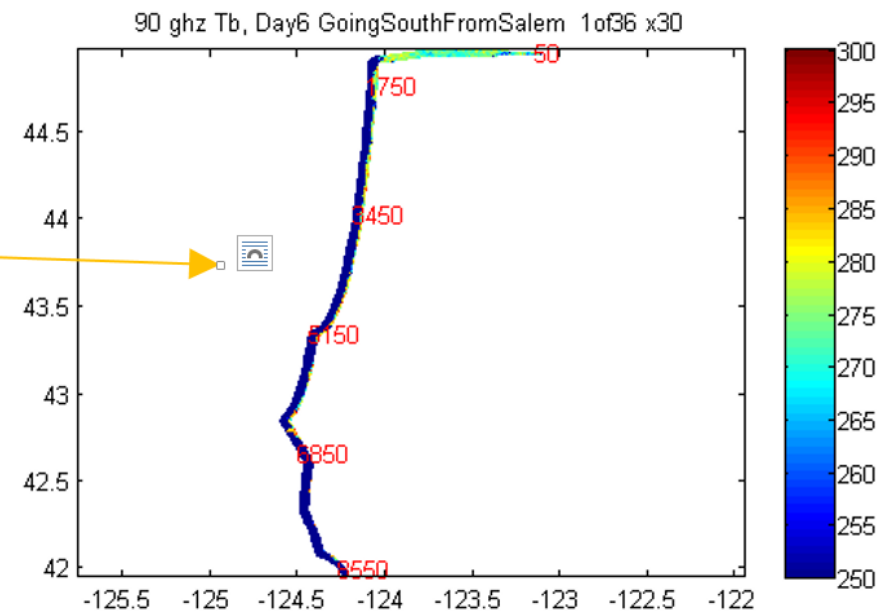
19,24,34 GHz microwave

90, 130, 168 GHz mmw window bands

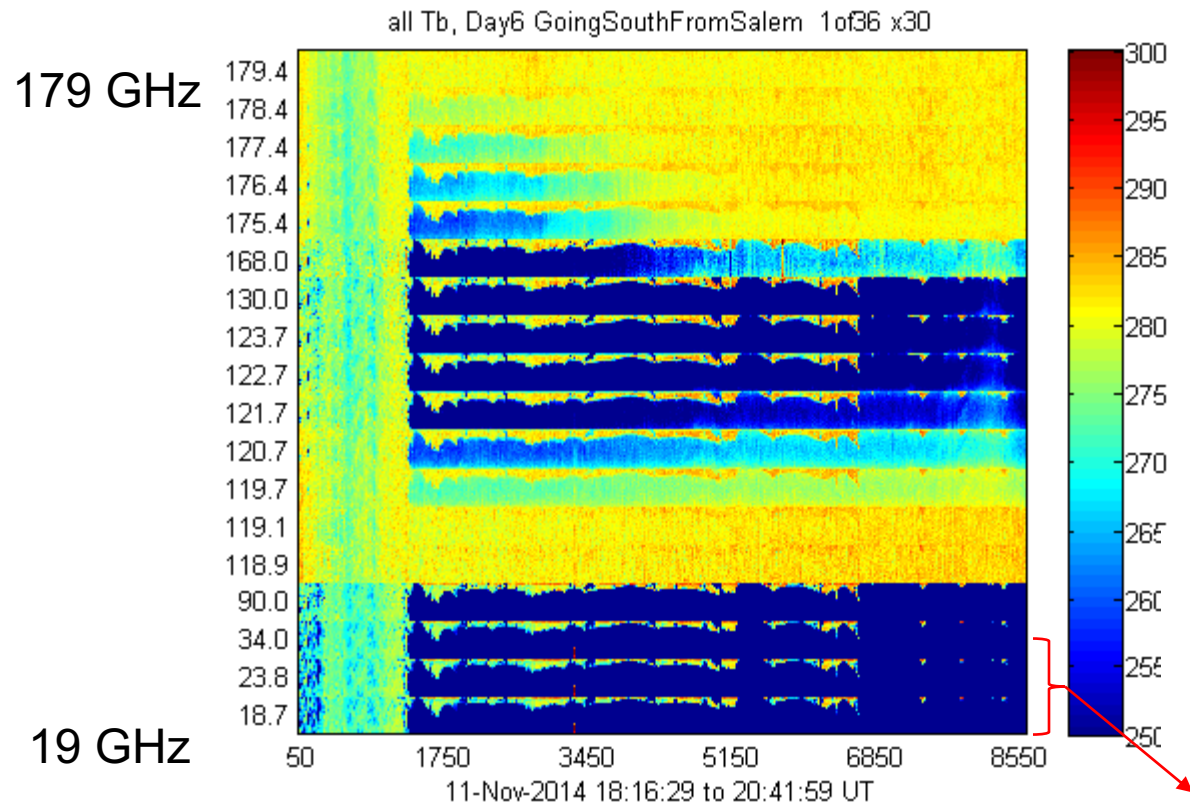
118-126 GHz oxygen sounding

175-183 GHz water vapor sounding

November, 2014 field campaign

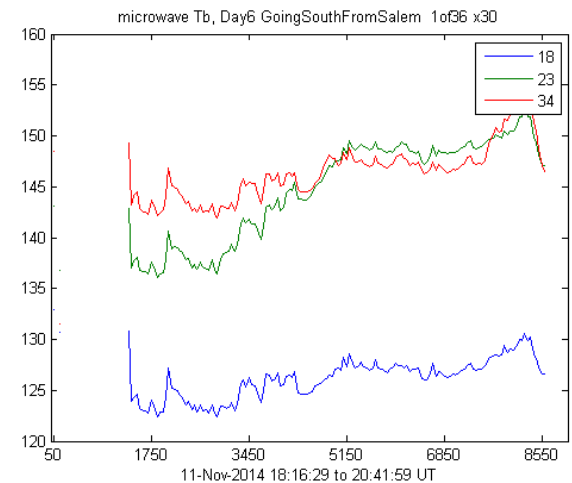


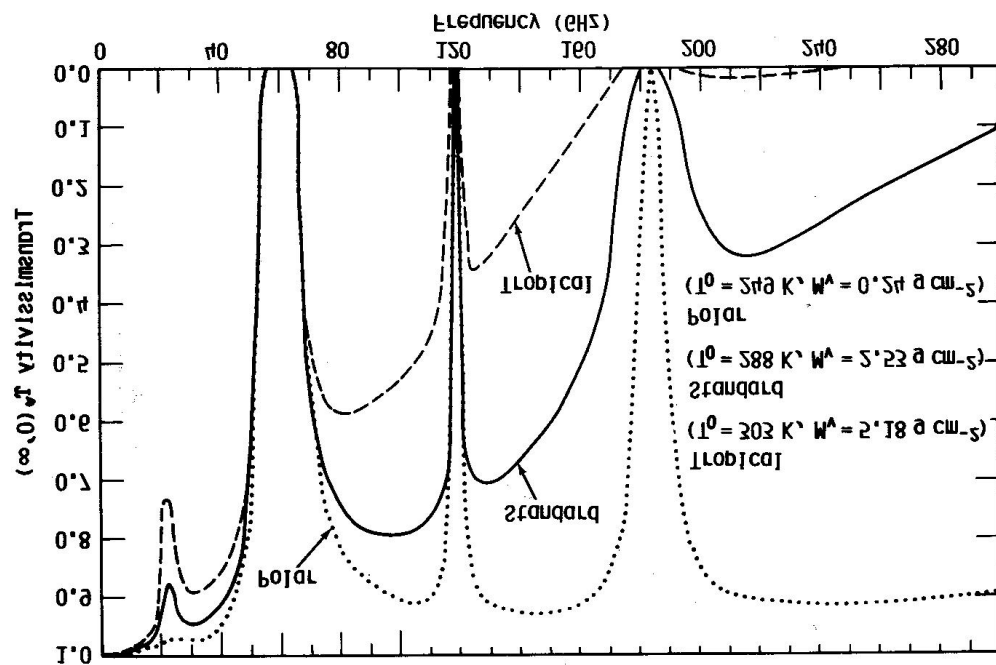
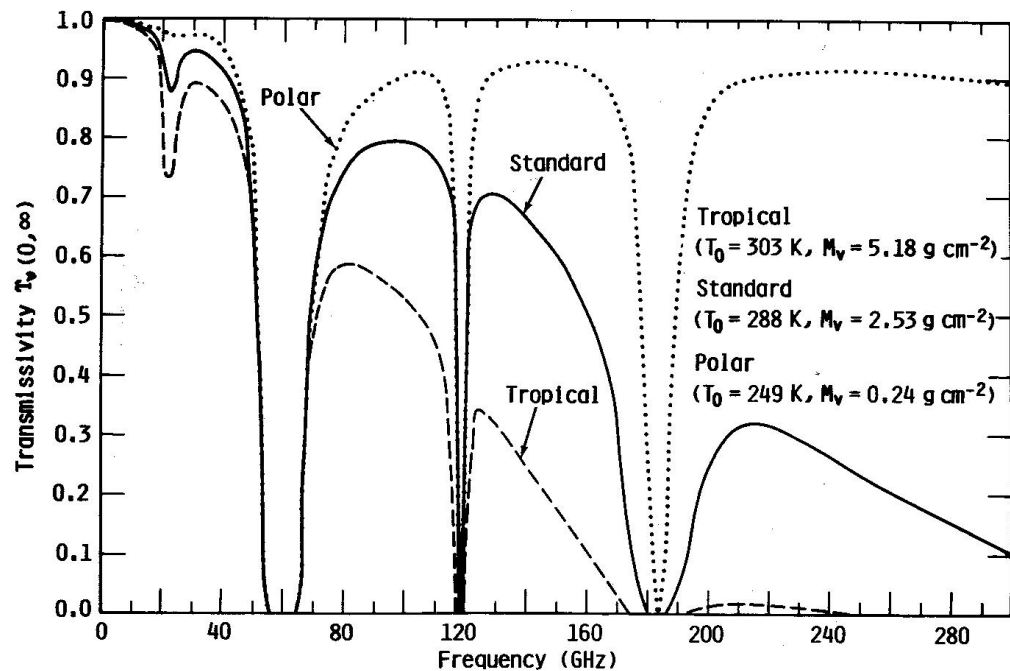
November 11, coastal example, sorted by RF frequency



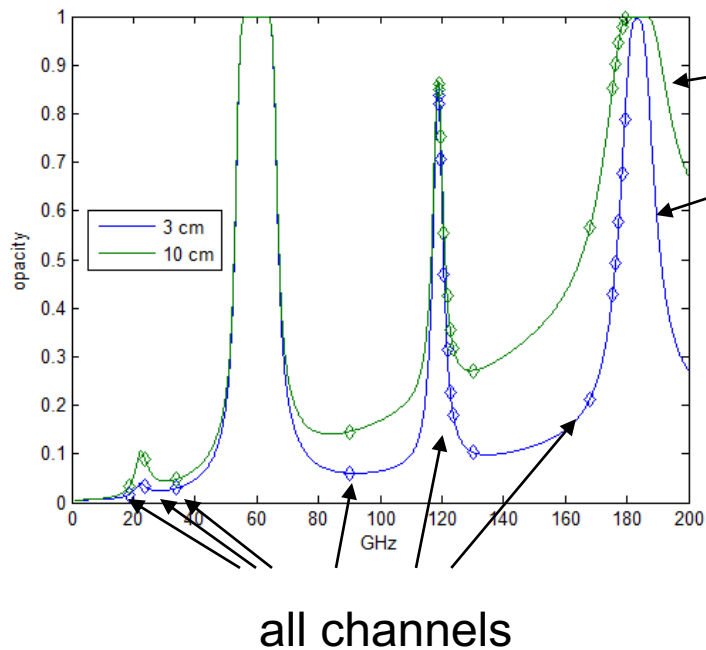
19 GHz

minima provide microwave
Tb for water vapor
retrieval= "ground truth"



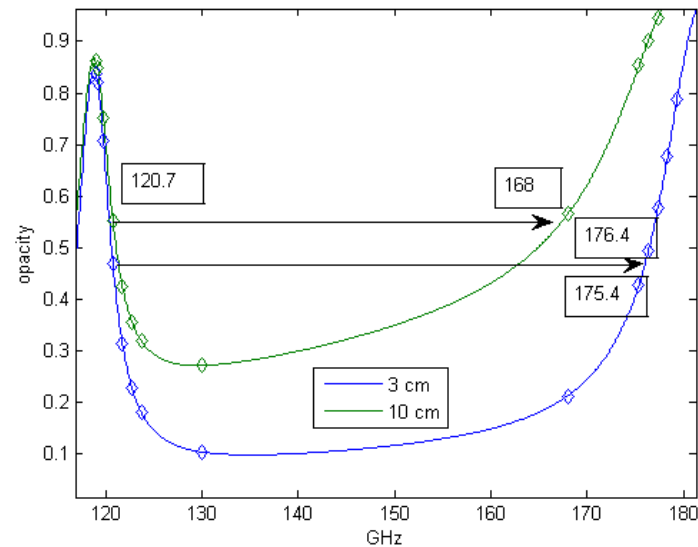


Retrieval is based on spectral models, with which oxygen is matched by opacity at given vapor level



green=10 cm wet path delay (PD)

blue = 5 cm PD



118-183

$$R_{ij} = R(f_i, PD_j) \equiv \frac{cov(T_{ij} - T_i, T_{90})}{\sqrt{var(T_{ij} - T_i)var(T_{90})}}$$

$$confidence \equiv \left(1 - \frac{RMSE}{PD}\right) \sum_i \frac{\partial R(f_i, PD)}{\partial PD} \Big|_{PD=PD_i}$$

$$0 = R(f_i, PD_i)$$

$$T_{ij} = \frac{o_{jk+1} - o_{ji}}{o_{jk+1} - o_{jk}} T_k + \frac{o_{ji} - o_{jk}}{o_{jk+1} - o_{jk}} T_{k+1}$$

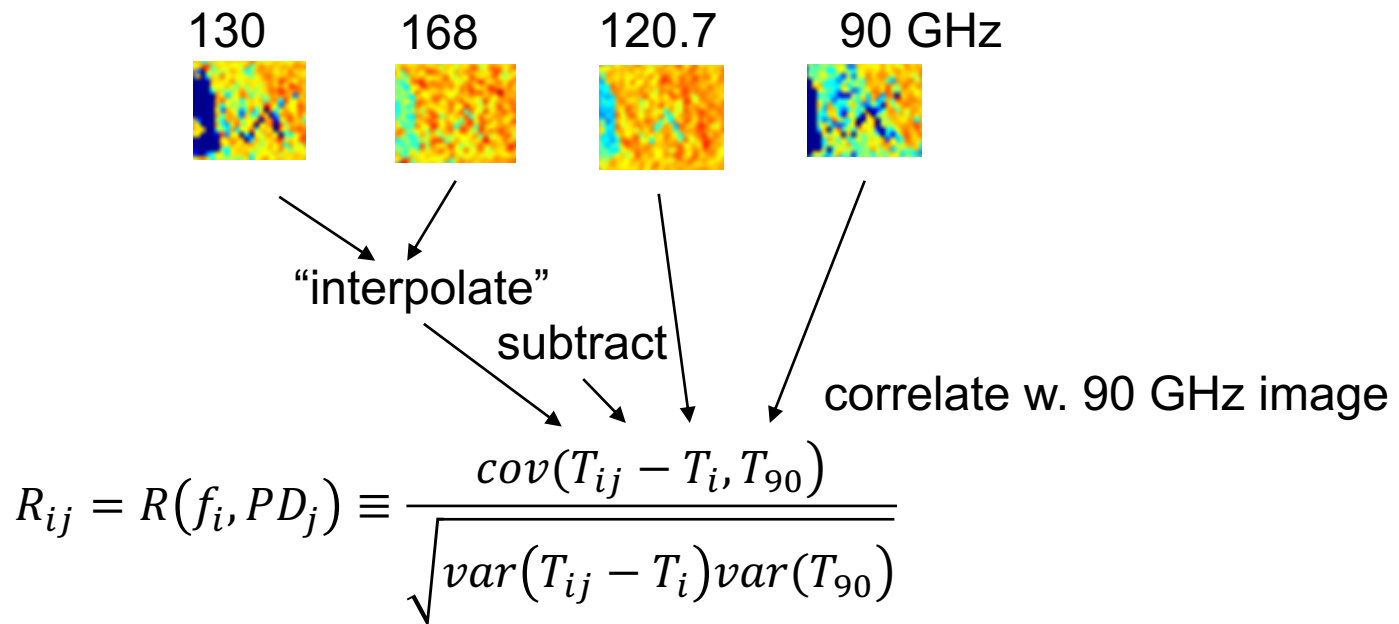
$$o_{jk} < o_{ji} < o_{jk+1}$$

$$RMSE = \sqrt{\frac{\sum_i (PD - PD_i)^2 * \frac{\partial R(f_i, PD)}{\partial PD} \Big|_{PD=PD_i}}{\sum_i \frac{\partial R(f_i, PD)}{\partial PD} \Big|_{PD=PD_i}}}$$

$$PD = \frac{\sum_i PD_i \frac{\partial R(f_i, PD)}{\partial PD} \Big|_{PD=PD_i}}{\sum_i \frac{\partial R(f_i, PD)}{\partial PD} \Big|_{PD=PD_i}}$$

step 1: Segment images into 2km x 2km cells (arbitrary choice for time being)

step 2: Compute correlation between clear surface map (e.g. at 90 GHz) and the difference between “interpolated” water channels and oxygen channel



What is meant by “interpolate”?

For each test case of total water vapor or path delay, PD_j , use atmospheric model to calculate three opacities, o_{ji} , o_{jk} , and o_{jk+1} at observed oxygen channel i , and vapor channels k and $k+1$ which satisfy

$$o_{jk} < o_{ji} < o_{jk+1}$$

then use model opacities to interpolate vapor channels to oxygen channel as

$$T_{ij} = \frac{o_{jk+1} - o_{ji}}{o_{jk+1} - o_{jk}} T_k + \frac{o_{ji} - o_{jk}}{o_{jk+1} - o_{jk}} T_{k+1}$$

Step 3:

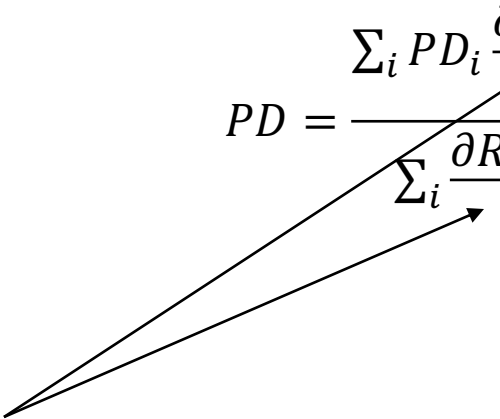
Vary PD to locate zero crossing in

$$0 = R(f_i, PD_i)$$

PD_i is now solution which produces match between oxygen channel i , and interpolated vapor channels.

Repeat steps 2 and 3 for all oxygen channels

step 4: Compute weighted mean of PD among all oxygen channels

$$PD = \frac{\sum_i PD_i \left. \frac{\partial R(f_i, PD)}{\partial PD} \right|_{PD=PD_i}}{\sum_i \left. \frac{\partial R(f_i, PD)}{\partial PD} \right|_{PD=PD_i}}$$


slope of correlation curves is proportional to signal strength, used as weighting

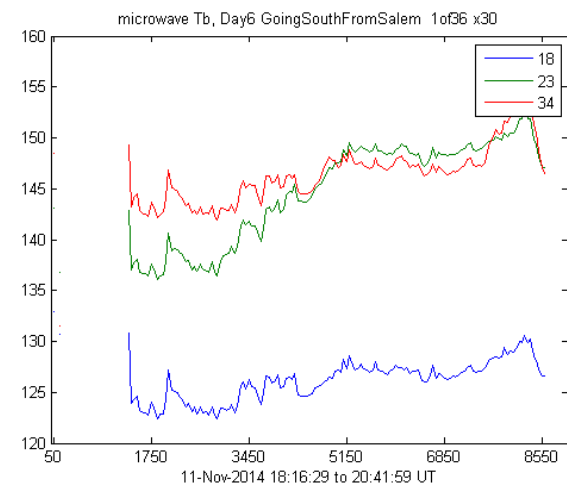
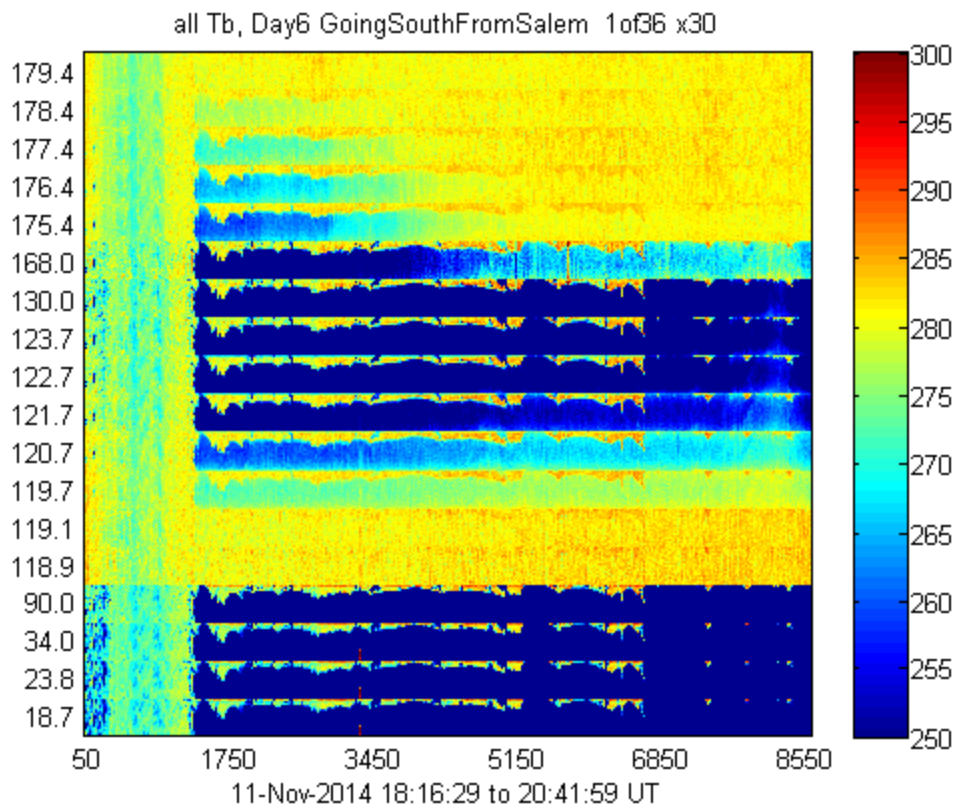
Also compute “quality metrics”

weighted RMS PD error among all oxygen channels (small= good):

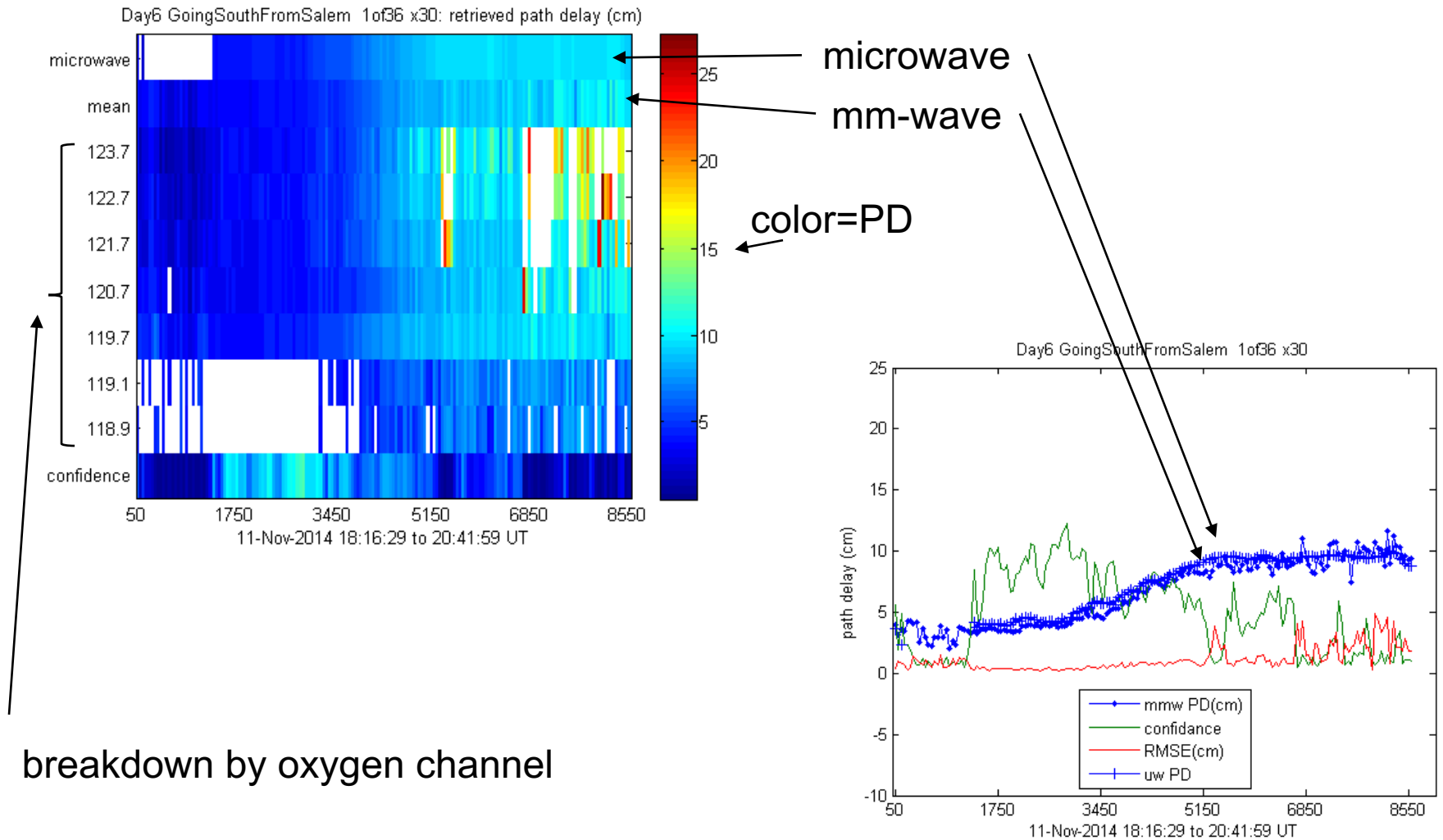
$$RMSE = \sqrt{\frac{\sum_i (PD - PD_i)^2 * \left. \frac{\partial R(f_i, PD)}{\partial PD} \right|_{PD=PD_i}}{\sum_i \left. \frac{\partial R(f_i, PD)}{\partial PD} \right|_{PD=PD_i}}}$$

and “confidence” metric (big = good):

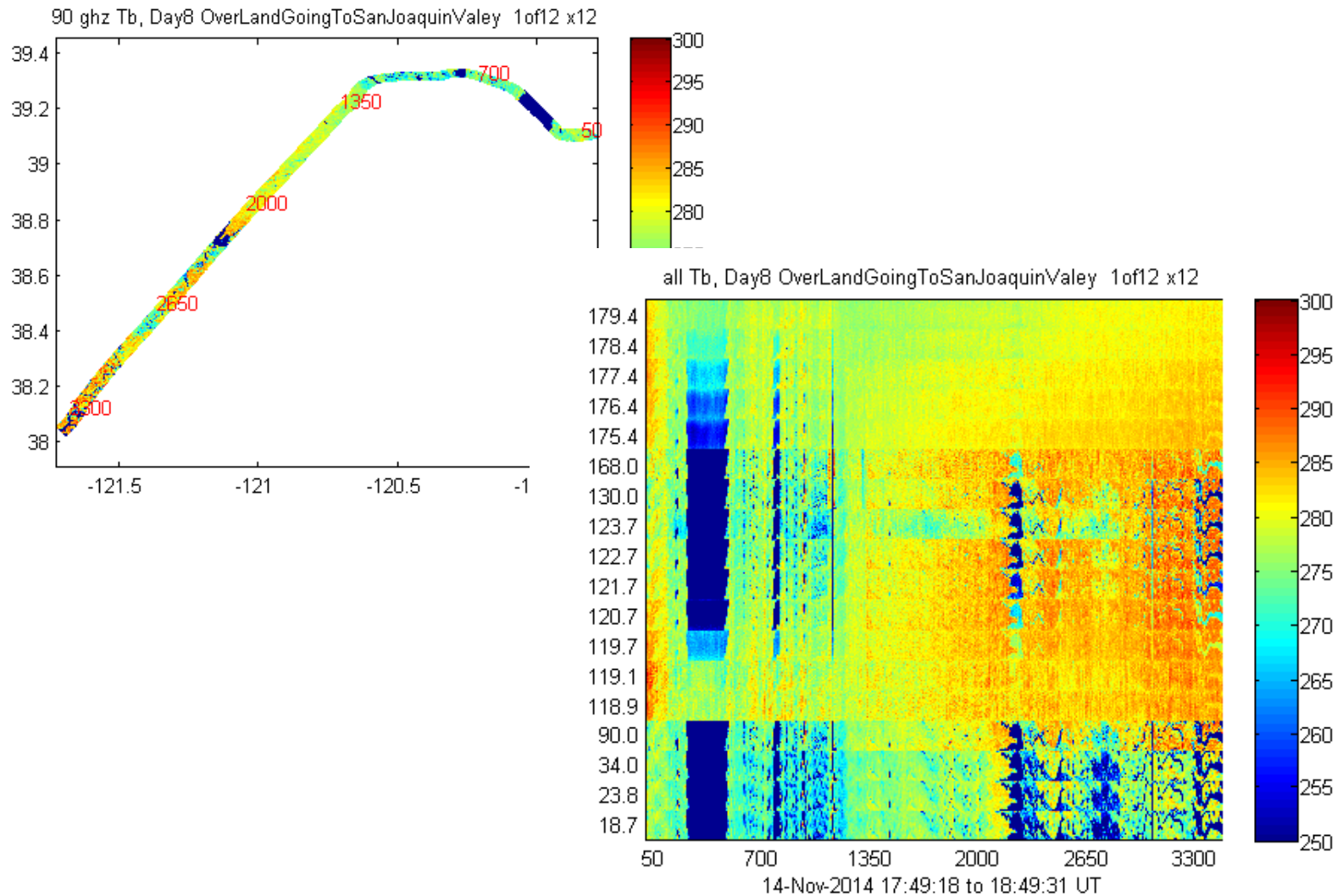
$$confidence \equiv \left(1 - \frac{RMSE}{PD}\right) \sum_i \left. \frac{\partial R(f_i, PD)}{\partial PD} \right|_{PD=PD_i}$$

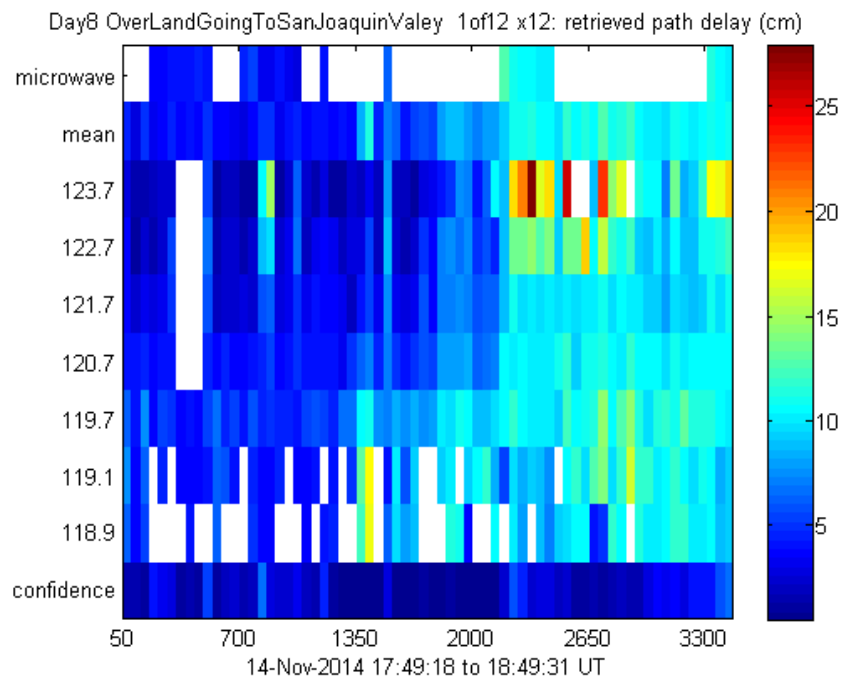


Solutions compared with 18-34 GHz microwave PD retrievals

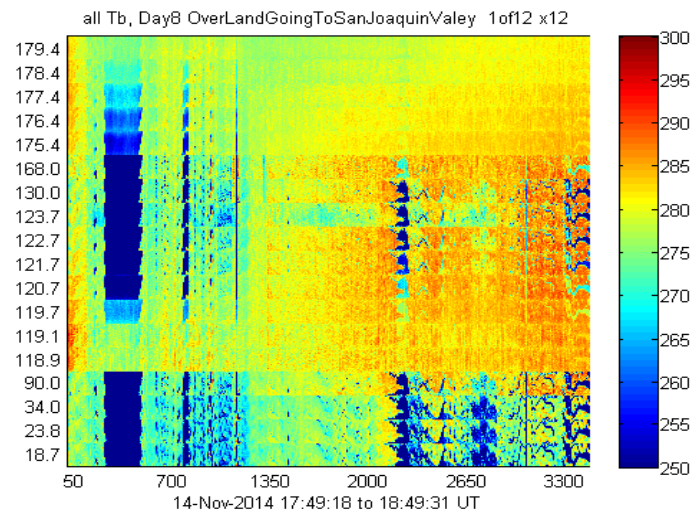
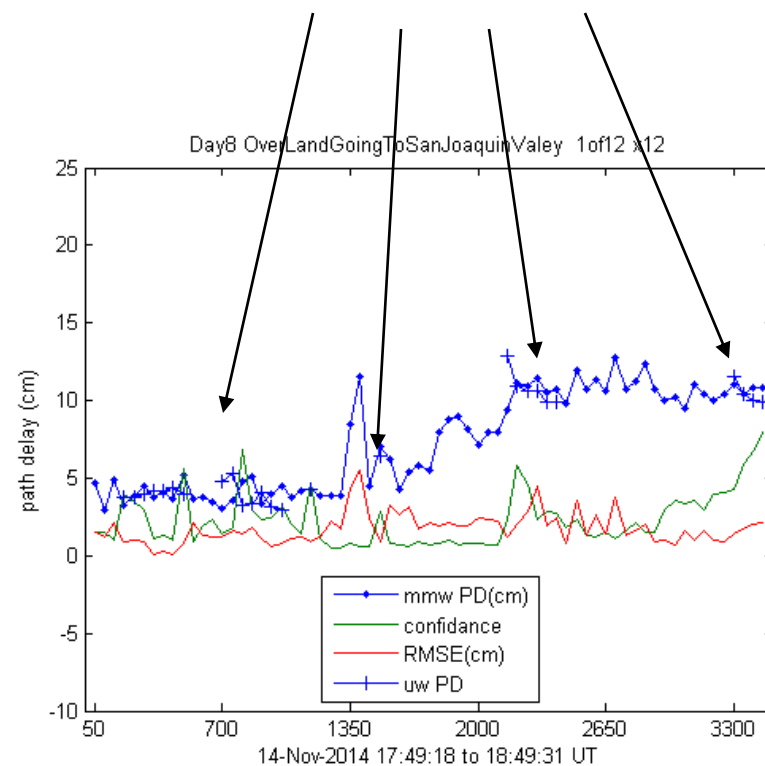


Another example: flying from Cason City NV, over Lake Tahoe, then into San Joaquin Valley, CA



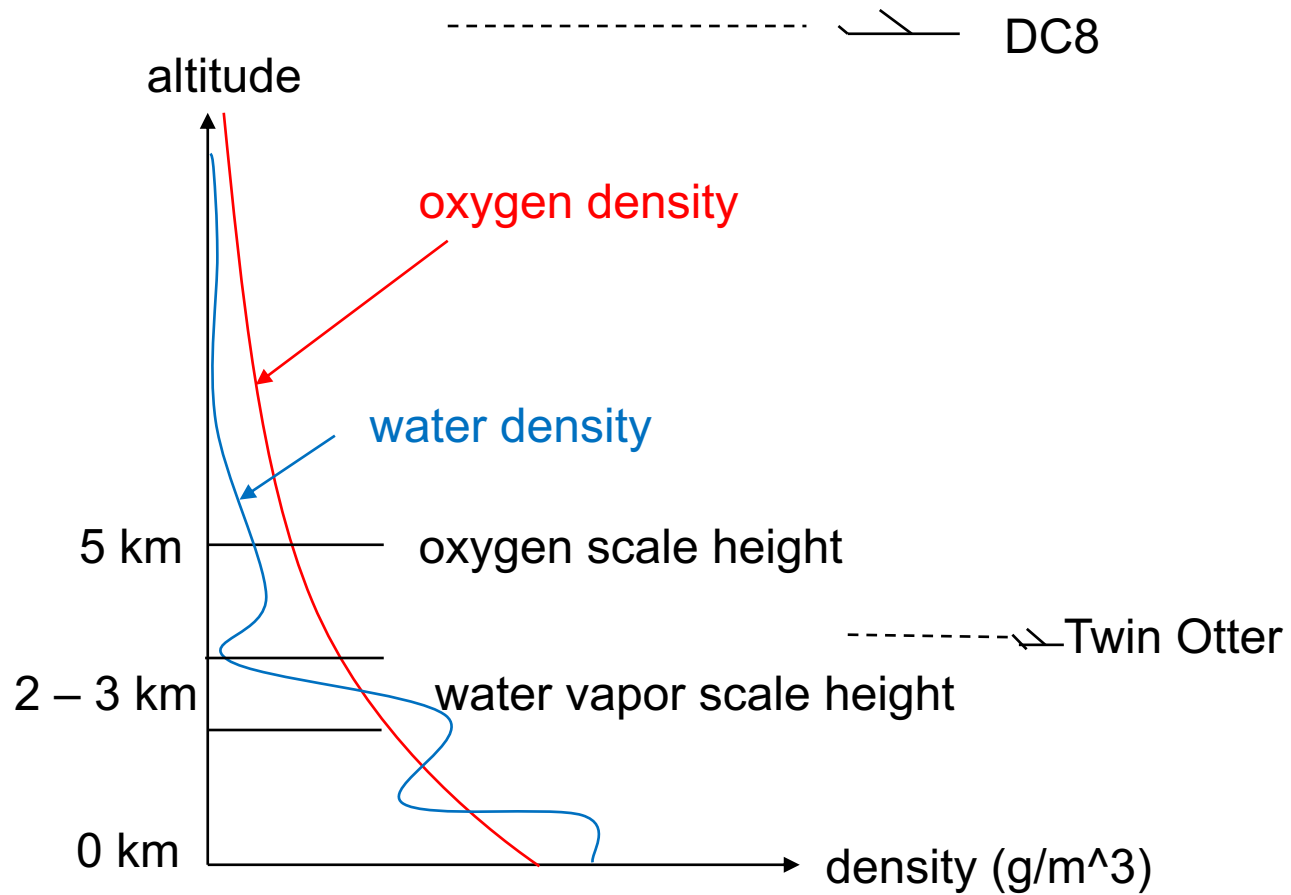


when we see open
water, matchup with
microwave is good!

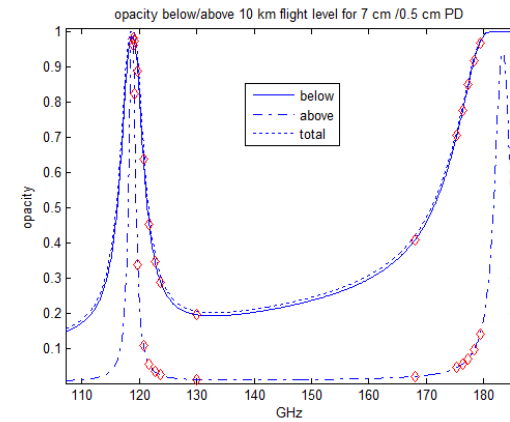
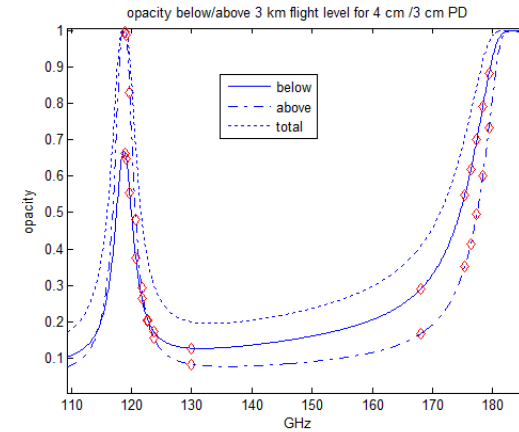


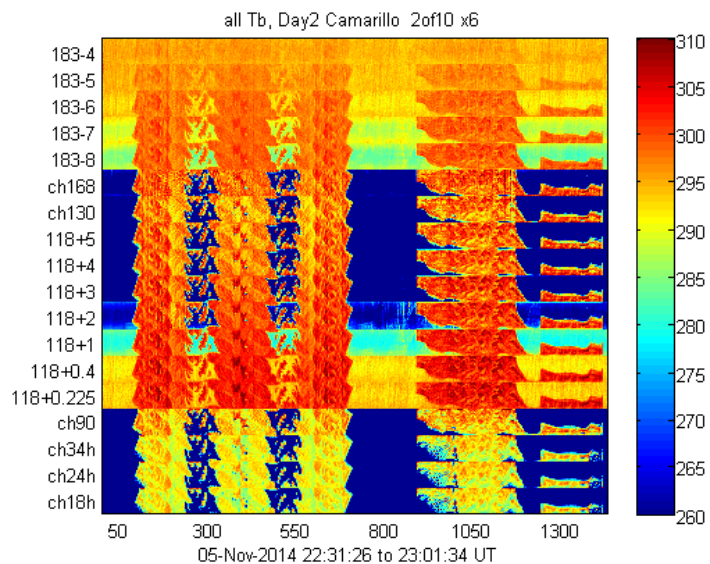
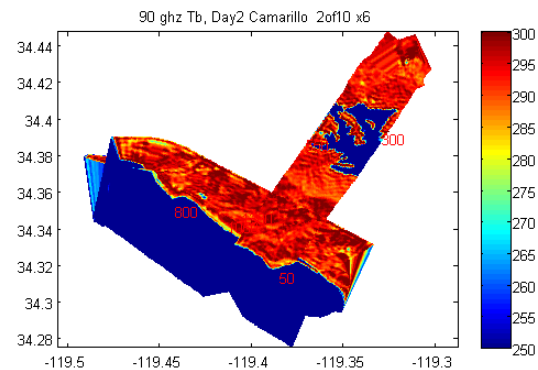
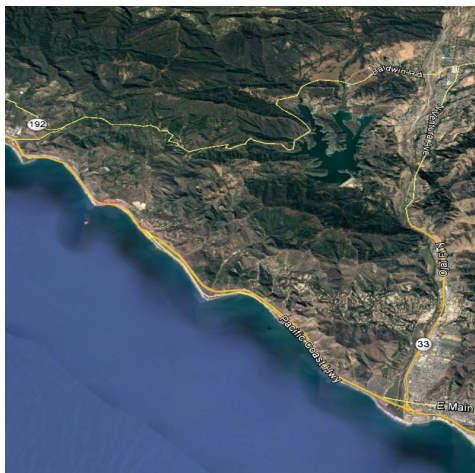
Technical issues remaining to address:

- Equal opacity but unequal downwelling temperature inevitable between oxygen and water, due to different vertical distributions. Tends to enhance scattering in oxygen bands. Multi-band comparison trends should provide correction.
- There is spectral ambiguity of continuum opacity vs PWV and path delay due to unknown vertical distribution. Mean water vs oxygen brightness temperatures, in addition to conventional soundings should be utilized to provide correction.
- Image segmentation presently arbitrary 2km x 2km. Better segmentation based on SNR metrics should improve spatial resolution and avoid erroneous retrievals in low SNR cases.
- Higher altitude needed so that majority of both oxygen and water are below observer.
- Need to test in high water vapor cases. Likely work better by adding 60 GHz bands to compare w 90 and 130 GHz continuum
- Should add 140 and 150 GHz bands



In Twin Otter, 3 km max altitude leaves
a lot of water and (more problematic)
more oxygen above aircraft





Day2 Camarillo 2of10 x6: retrieved path delay (cm)

